

MULTI-STAGE CLICK SWITCH

BACKGROUND OF THE INVENTION

This invention relates to an improved multi-stage click
5 switch which produces a suitable click feeling in a multi-stage
manner when operating an operation knob.

As shown in Figs. 9 and 10, one example of related switches
for controlling the operation of various electric equipments
10 (such as a power window mechanism), mounted, for example, on
a door trim of a car door, is a two-stage click switch 1 which
produces a suitable click feeling when pivotally operating an
operating knob 11.

15 This two-stage click switch 1 disclosed in Japanese Patent
No. 2792571, comprises: a housing 2; a pair of pressing members
10 and 12 forwardly and backwardly-movably mounted on the housing
2 in spaced relation to each other; the operating knob 11 for
moving the pressing members 10 and 12 downward; a contact circuit
20 member 3, which is mounted on the housing 2 in opposed relation
to the pressing members 10 and 12 and the operating knob 11,
and has two pairs of contact portions 14a, 14b and 16a, 16b
each pair of which are disposed in opposed relation to a
respective one of the pressing members 10 and 12; and a rubber
25 switch member 9 provided between the contact circuit member

3 and the pressing members 8 and 10.

The rubber switch member 9 has two pairs of rubber contact portions 5a, 5b and 7a, 7b each pair of which can sequentially close and open the corresponding pair of contact portions 14a and 14b (16a and 16b) upon forward and backward movement of the corresponding pressing member 8, 10. A pair of conductive pieces 6a and 6b (8a and 8b) are provided within each pair of rubber contact portions 5a and 5b (7a and 7b), respectively, in opposed relation to the contact portions 14a and 14b (16a and 16b). The distance L_1 between the conductive piece 6a, 8a and the contact portion 14a, 16a is smaller than the distance L_2 between the other conductive piece 6b, 8b and the contact portion 14b, 16b ($L_1 < L_2$).

The rubber contact portion 5a, 7a, after pressed into contact with the contact portion 14a, 16a, can still advance a small distance, and the rubber contact portion 5a, 7a of the overstroke type can absorb an operating stroke difference due to the distances L_1 and L_2 . Namely, the rubber contact portion 5a, 7a includes two-stage operating means 19 which is operable in a two-stage manner while absorbing the operating stroke difference.

The operating knob 11 is pivotally supported by a pair

of support shafts 2a and 2a formed on the housing 2. The operating knob, when pivotally moved in a clockwise direction (Fig. 9), advances the pressing member 12, thereby moving a window glass pane upward, and when this operating knob is pivotally moved
5 in a counterclockwise direction, it advances the pressing member 10, thereby moving the window glass pane downward.

For example, when the operating knob 11 is pivotally moved in the clockwise direction (Fig. 9), the pressing member 12
10 advances downward to descend the rubber contact portions 7a and 7b. In this descending operation, the conductive piece 8a is first pressed into contact with the manually-ascending contact portion 16a to achieve a first-stage operating condition, thereby rendering this contact portion into a conducting state.
15 When this condition is maintained, the window glass pane is ascending.

Then, when the operating knob 11 is returned to its initial position, the conductive piece 8a moves upward apart from the contact portion, so that the window glass pane ceases to ascend.
20 Alternatively, when the operating knob 11 is further pivotally moved through a predetermined angle in the clockwise direction, the rubber contact portion 7a, serving as the two-stage operating means 19, is further flexed after the above press contact, thereby absorbing the stroke difference, so that the rubber
25 contact portion 7b continues to descend, and the conductive

piece 8b is pressed into contact with the automatically-ascending contact portion 16b to achieve a second-stage operating condition, and the window glass pane automatically moves upward to an upper limit.

5

In the case of the switch thus operable in a two-stage manner, unless a click feeling, capable of detecting the operating condition of each stage, is provided, an operation error is incurred.

10

Therefore, the operating knob 11 is provided with a click producing mechanism 18 which comprises a compression spring 15 and a pin 13 which are provided in a mounting hole provided at a central portion of the operating knob. A suitable click feeling can be obtained by the friction between the pressing pin 13 and a V-shaped receiving groove 17. Each of the rubber contact portions 5a, 5b, 7a and 7b has a generally bowl-shaped cross-section, and is of the clickless type so as to be elastically deformed without affecting a click feeling produced by the click producing mechanism 18.

20

However, since the pressing pin 13 and the compression spring 15 of the click producing mechanism 18 are contained in the operating knob 11, the height dimension of the operating knob 11 increases.

25

Therefore, the pressing member 10, 12 for transmitting

a plurality of pressing portions provided on the operating knob;

a contact circuit member including a plurality of switch contact portions disposed in opposed relation to the plurality of pressing portions, respectively;

a rubber switch member provided between the plurality of pressing portions and the contact circuit member;

a plurality of rubber contact portions which are formed on the plurality of rubber switch member, and can sequentially close and open the switch contact portions in multi-stage manner in accordance with the movement of the plurality of pressing portions, wherein each of the plurality of rubber contact portions produces a click feeling by a resilient force, produced by elastic deformation of the rubber contact portion during the movement of the operating knob, at the time of operating the operating knob, and includes a conductive piece opposed to corresponding one of the plurality of switch contact portions; and

over stroke means which is capable of elastic deformation of a lower resilient force, not producing a click feeling, and is provided to the at least one rubber contact portion except the at least one rubber contact portion effecting a final-stage switching operation, for allowing the movement of the operating knob until the final-stage switching operation is completed.


In the above construction, a click feeling is produced by the resilient force produced when the rubber contact portion itself is elastically deformed, and therefore it is not necessary to provide a click producing mechanism, comprising special parts,
5 as used in the conventional switch.

Therefore, the number of the component parts, as well as the time and labor for the assembling operation, is reduced, so that the production cost can be reduced. And besides, it is not necessary to provide such a click producing mechanism,
10 comprising separate members, between the operating knob and the rubber switch member, and therefore the whole of a switch unit can be formed into a compact design.

A click feeling can be easily produced in a multi-stage manner in accordance with the number of the rubber contact
15 portions.

The operating knob is pivotally mounted on the housing, and the plurality of pressing portions are formed on and project from the reverse surface of the operating knob at
20 pivotally-moving opposite end portions thereof. With this construction, there can be provided the multi-stage click switch of the pivotally-moving type which is compact and inexpensive.

BRIEF DESCRIPTION OF THE DRAWINGS

 Fig. 1 is a cross-sectional view of a first embodiment

of a multi-stage click switch of the present invention.

Fig. 2 is a cross-sectional view taken along the line II-II of Fig. 1.

Fig. 3 is an enlarged, cross-sectional view of an important
5 portion, taken along the line III-III of Fig. 2.

Fig. 4 is a partly-broken, perspective view of a rubber switch member shown in Fig. 3.

10 Figs. 5A and 5B are cross-sectional views explanatory of an overstroke operation of a rubber contact portion shown in Fig. 3.

15 Fig. 6 is a vertical cross-sectional view showing the positional relation between the rubber contact portion and a rubber switch pressing portion in a first-stage switch-operating condition of the multi-stage click switch of Fig. 1.

Fig. 7 is a cross-sectional view explanatory of the operation of the multi-stage click switch of Fig. 1.

Fig. 8 is a vertical cross-sectional view of a second embodiment of a multi-stage click switch of the invention.

20 Fig. 9 is a vertical cross-sectional view of a related two-stage click switch.

Fig. 10 is a vertical cross-sectional view taken along the line X-X of Fig. 9.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

One preferred embodiment of a multi-stage click switch of the present invention will now be described in detail with reference to the accompanying drawings.

5 Figs. 1A and 1B are a cross-sectional view of the multi-stage click switch according to the first embodiment of the invention, Fig. 2 is a cross-sectional view taken along the line II-II of Fig. 1, Fig. 3 is an enlarged, cross-sectional view of an important portion, taken along the line III-III of
10 Fig. 2, Fig. 4 is a partly-broken, perspective view of a rubber switch member shown in Fig. 3, Figs. 5A and 5B are a cross-sectional views explanatory of an overstroke operation of a rubber contact portion shown in Fig. 3, and Figs. 6A, 6B, 7A and 7B are cross-sectional views explanatory of the operation
15 of the multi-stage click switch of Fig. 1.

The multi-stage click switch 21 according to this first embodiment is a pivotally-moving switch capable of achieving a two-stage click operation, and this multi-stage click switch
20 of the pivotally-moving type can be suitably used, for example, as a switch for a power window of a vehicle.

As shown in Figs. 1 and 2, the multi-stage click switch 21 in this first embodiment comprises: a housing 32; an operating knob 35 pivotally mounted by support shafts 33 of the housing
25 32; two pairs of forwardly and backwardly-movable pressing

portions 36a, 36b and 37a, 37b each pair of which are formed on and project from a reverse surface of the operating knob 35 at a respective one of pivotally-moving opposite end portions thereof; a contact circuit member 25 having a plurality of switch contact portions 41a, 41b, 42a and 42b disposed in opposed relation to the pressing portions 36a, 36b, 37a and 37b, respectively; the rubber switch member 30 provided between the contact circuit member 25 and the pressing portions 36a, 36b, 37a and 37b; and two pairs of rubber contact portions 28a, 28b and 29a and 29b which are formed on the rubber switch member 30, and each pair of rubber contact portions 28a and 28b (29a and 29b) can sequentially close and open the corresponding switch contact portions 41a and 41b (42a and 42b) in a multi-stage manner (in a two-stage manner in this embodiment) in accordance with the forward and backward movement of the corresponding pressing portions 36a and 36b (37a and 37b). This multi-stage click switch is covered by upper and lower casings 34 and 31.

A pair of conductive pieces 22a and 22b (23a and 23b) are provided within each pair of rubber contact portions 28a and 28b (29a and 29b), respectively, in opposed relation to the contact portions 41a and 41b (42a and 42b).

The two pressing portions 36a and 36b for sequentially depressing the pair of rubber contact portions 28a and 28b are formed on and project from the reverse surface of the operating

knob 35 at one longitudinal end portion thereof (left end portion in Fig. 1), and the two pressing portions 37a and 37b for sequentially depressing the pair of rubber contact portions 29a and 29b are formed on and project from the reverse surface of the operating knob 35 at the other longitudinal end portion thereof (right end portion in Fig. 1).

The distal end of each of the pressing portions 36a, 36b, 37a and 37b is formed into such an inclined shape that when it abuts against the rubber contact portion 28a, 28b, 29a, 29b, its abutment surface is disposed generally perpendicularly to the pressing direction.

The operating knob 35 is pivotally supported by the pair of support shafts 33 and 33 formed on the housing 32. The operating knob, when pivotally moved in a clockwise direction (Fig. 1), advances the pressing portions 37a and 37b, thereby moving a window glass pane upward, and when this operating knob is pivotally moved in a counterclockwise direction, it advances the pressing portions 36a and 36b, thereby moving the window glass pane downward.

In the multi-stage click switch 21 in this first embodiment which is the switch for the power window, the two rubber contact portions 28a and 28b, disposed at the left end portion of Fig. 2 as indicated in an image line, are used for descending the

window glass pane, and the two rubber contact portions 29a and 29b, disposed at the right end portion of Fig. 2, are used for ascending the window glass pane.

The rubber contact portion 28a, 29a, disposed at the upper
5 portion of Fig. 2, is used for the first-stage switching operation, and the rubber contact portion 28b, 29b, disposed at the lower portion of Fig. 2, is used for the second-stage switching operation.

10 As shown in Fig. 3, a space between the rubber contact portion 28a, 29a for the first-stage switching operation and the opposing pressing portion 36a, 37a, and a space between the rubber contact portion 28b, 29b for the second switching operation and the opposing pressing portion 36b, 37b are
15 different from each other so that the rubber contact portions 28a (29a) and 28b (29b) can be sequentially brought into contact with the switch contact portions 41a (42a) and 41b (42b) in accordance with the depressing operation of the operating knob 35. Therefore, the timing of contact of the first-stage rubber
20 contact portion 28a, 29a with the corresponding pressing portion is different from the timing of contact of the second-stage rubber contact portion 28b, 29b with the corresponding pressing portion.

25 Unlike the rubber contact portions 5a, 5b, 7a and 7b shown

in Fig. 9, each of the rubber contact portions 28a, 28b, 29a and 29b of this embodiment has a generally conical cross-section (as shown in Fig. 3) so that its resilient force, produced when it is elastically deformed upon descending of the corresponding pressing portion 36a, 36b, 37a, 37b, produces a suitable click feeling at the time of operating the operating knob 35.

In this first embodiment, each of the rubber contact portions 28a and 29a, other than the rubber contact portions 28b and 29b for effecting the final-stage (second-stage in this embodiment) switching operation, has overstroke means by which after its conductive piece 22a, 23a contacts the opposing switch contact portion 41a, 42a, the rubber contact portion 28a, 29a allows the forward movement of the pressing portion 36a, 37a because of its elastic deformation of a low resilient force, not producing a click feeling, until the final-stage switching operation by the rubber contact portion 28b, 29b is completed.

Namely, as shown in Figs. 3 to 5B, the outer end portion (upper end portion in the drawings) of the rubber contact portion 28a, 29a, which can be pressed by the pressing portion 36a, 37a, is formed into a cylindrical tubular portion having an inner diameter larger than the outer diameter of the inner end portion (lower end portion in the drawings) having the conductive piece 22a, 23a mounted thereon. This cylindrical tubular

portion is displaced downward uniformly around the inner end portion while flexing a thin wall portion 43 of a conical shape flaring from the outer end portion. With this construction, the rubber contact portion 28a, 29a has the overstroke means
5 by which it can effect elastic deformation of a lower resilient force, not producing a click feeling, when its stroke exceeds a predetermined value.

In the construction having such overstroke means, when
10 the pressing portion 36a (not shown) is further moved downward from the first-stage switch-operating condition shown in Fig. 5A, the outer end portion of the rubber contact portion 28a for effecting the first-stage switching operation can descend a distance S because of the low resilient-force elastic
15 deformation of the thin wall portion 43, with the conductive piece 22a (formed on the inner end portion of this rubber contact portion 28a) held against the switch contact portion 41a, as shown in Fig. 5B, and thus the rubber contact portion 28a allows the downward movement of the pressing portion 36a without
20 producing a click feeling.

The outer end portion of the rubber contact portion 28b, 29b for effecting the second-stage switching operation is formed into a solid construction, and is not provided with such overstroke means as described above for the rubber contact
25 portions 28a and 29a.

Next, the operation of the multi-stage click switch 21 of this first embodiment will be described. In the initial condition of the multi-stage click switch 21 before the pressing operation, the outer end portion of the first-stage-operating rubber contact portion 28a, 29a is held in slight contact with the distal end of the opposing pressing portion 36a, 37a as shown in Fig. 1A, and the operating knob 35 is maintained in a neutral condition by resilient contact forces of the rubber contact portions 28a and 29a.

In this initial condition, the outer end portion of the second-stage-operating rubber contact portion 28b, 29b is spaced a small distance from the distal end of the opposing pressing portion 36b, 37b, as shown in Fig. 1B.

In the initial condition of the multi-stage click switch 21, when the one end portion (left end portion in Fig. 6A) is pressed, so that the first-stage-operating rubber contact portion 28a is depressed a predetermined amount by the pressing portion 36 as shown in Fig. 6A. This rubber contact portion 28a produces a suitable click feeling by the resilient force of the elastically-deformed thin wall portion 43 at the time of operating the operating knob 35, and at the same time the conductive piece 22a is brought into contact with the switch contact portion 41a, thereby achieving the first-stage

Rubbery
Contact
Not
wall

switch-operating condition.

Namely, when the thin wall portion 43 of the rubber contact portion 28a is elastically deformed in an amount larger than the predetermined value, this thin wall portion 43 is buckled, so that the resilient reaction force, transmitted to the operating knob 35, is reduced, and therefore the operator can perceive this as a click feeling representing the first-stage switching operation.

In this first-stage switch-operating condition, the pressing portion 36b is brought into contact with the outer end portion of the second-stage-operating rubber contact portion 28b for the first time as shown in Fig. 6B, and when the operating knob 35 is further pressed down, this rubber contact portion begins to be depressed.

When the operating knob 35 is further pressed down from the first-stage switch-operating condition, the first-stage-operating rubber contact portion 28a allows the downward movement of the pressing portion 36a because of the elastic deformation of the thin wall portion 43 (forming the overstroke means), with the conductive piece 22a held in contact with the switch contact portion 41a, as shown in Fig. 7.

When the second-stage-operating rubber contact portion

28b is depressed by the pressing portion 36b in an amount larger than the predetermined value as shown in Fig. 7B, this rubber contact portion produces a suitable click feeling by the resilient force of an elastically-deformed thin wall portion 43 thereof at the time of operating the operating knob 35, and at the same time the conductive piece 22b is brought into contact with the switch contact portion 41b, thereby achieving a second-stage switch-operating condition.

Therefore, for example, when the operating knob 35 is pivotally moved in a counterclockwise direction (Fig. 1), the pressing portions 36a and 36b move forward, and the conductive piece 22a of the rubber contact portion 28a is first pressed into contact with the switch contact portion 41a (serving as the manually-descending contact portion) to achieve the first-stage operating condition, thereby rendering this switch contact portion into a conducting state. When this condition is maintained, the window glass pane is descending.

Then, when the operating knob 35 is returned to its initial position, the conductive piece 22a moves upward apart from the switch contact portion, so that the window glass pane ceases to descend. Alternatively, when the operating knob 35 is further pivotally moved through a predetermined angle in the counterclockwise direction, the thin wall portion 43 of the rubber contact portion 28a, having the overstroke means, is

further flexed without producing a click feeling, and absorbs the stroke difference, and therefore the rubber contact portion 28b continues to be depressed, and the conductive piece 22b is pressed into contact with the switch contact portion 41b (serving as the automatically-descending contact portion) to achieve a second-stage operating condition, and the window glass pane automatically descends to a lower limit.

Namely, in the multi-stage click switch 21 of this first embodiment, a click feeling is produced by the reaction force produced as a result of elastic deformation of each of the rubber contact portions 28a, 28b, 29a and 29b. Therefore, it is not necessary to provide the click producing mechanism 18, comprising the special parts as in the related two-stage click switch 1 shown in Fig. 9.

Therefore, in the multi-stage click switch 21 in this first embodiment, the number of the component parts is reduced, and the time and labor, required for the assembling operation, is reduced, so that the production cost can be reduced. And besides, it is not necessary to provide a click producing mechanism, comprising separate members, between the operating knob 35 and the rubber switch member 30, and therefore the height dimension of the operating knob 35 can be reduced, so that the whole of the switch unit can be formed into a compact design.

By increasing the number of the rubber contact portions

28a, 28b, a click feeling can be easily produced in a multi-stage manner, that is, two- or more stage manner.

Although the multi-stage click switch 21 of the first
5 embodiment is the pivotally-moving switch which is operated by pressing the opposite end portions of the operating knob 35, the present invention is not limited to this multi-stage click switch.

For example, a second embodiment of a push-type
10 multi-stage click switch 51 of the present invention, shown in Fig. 8, comprises: a pair of pressing portions 56a and 56b of different heights mounted on a reverse surface of an operating button (operating knob) 52 upwardly and downwardly-movably mounted on a housing 55; a contact circuit member 53, which
15 has a pair of switch contact portions 59a and 59b which are disposed in opposed relation to the pressing portions 56a and 56b; a rubber switch member 54 provided between the contact circuit member 53 and the pressing portions 56a and 56b; and
20 a pair of rubber contact portions 57a and 57b which are formed on the rubber switch member 54, and can sequentially close and open the switch contact portions 59a and 59b in a two-stage manner in accordance with the forward and backward movement of the pressing portions 56a and 56b.

25 A resilient force, produced when each rubber contact

portion 57a, 57b is elastically deformed by the forward movement of the pressing portion 56a, 56b, produces a suitable click feeling at the time of operating the operating button 52. Conductive pieces 58a and 58b are formed respectively on the inner sides of the rubber contact portions 57a and 57b in opposed relation to the switch contact portions 59a and 59b, respectively.

The first-stage switch-operating rubber contact portion 57a, operated by the pressing portion 56a, has overstroke means by which after its conductive piece 58a contacts the opposing switch contact portion 59a, the rubber contact portion 57a allows the forward movement of the pressing portion 56a because of its elastic deformation of a low resilient force, not producing a click feeling, until the second-stage switching operation of the rubber contact portion 57b by the pressing portion 56b is completed. As described above for the rubber contact portion 28a (29a) of the multi-stage click switch 21 of the first embodiment, this overstroke means is formed by a cylindrical tubular outer end portion of the rubber contact portion 57a and a thin wall portion 44 of a conical shape flaring from this outer end portion.

Namely, in the multi-stage click switch 51 of this second embodiment, a click feeling is produced by the resilient force

produced when the rubber contact portion 57a itself is elastically deformed as in the multi-stage click switch 21 of the first embodiment.

Therefore, it is not necessary to provide a click producing mechanism, comprising special parts, and the number of the component parts, as well as the time and labor for the assembling operation, is reduced, so that the production cost can be reduced, and besides the whole of the switch unit can be formed into a compact design.

A click feeling can be produced in a multi-stage manner in accordance with the number of the rubber contact portions 57a, 57b.

In the multi-stage click switches 21 and 51 in the above embodiments, although the overstroke means is formed by the cylindrical tubular outer end portion of the rubber contact portion and the thin wall portion flaring from this outer end portion, this means of the present invention is not limited to this construction, but can take any other suitable form.

For example, there can be used a construction in which when a cylindrical tubular outer end portion of the rubber contact portion is pressed by a force larger than a predetermined value, this outer end portion itself is buckled and deformed so as to absorb the stroke difference between this rubber contact portion and the final-stage rubber contact portion.

In the multi-stage click switches 21 and 51 in the above embodiments, although an FPC (flexible printed circuit) is used as the contact circuit member 25, 53 in order to form the whole of the switch unit into a thinner design, any other suitable contact circuit member, such as a PCB (printed circuit board), can be used.

In the above-mentioned multi-stage click switch in the present invention, a click feeling is produced by the resilient force produced when the rubber contact portion itself is elastically deformed. Therefore, it is not necessary to provide a click producing mechanism, comprising special parts, as used in the related switch.

Therefore, the number of the component parts, as well as the time and labor for the assembling operation, is reduced, so that the production cost can be reduced. And besides, it is not necessary to provide such a click producing mechanism, comprising separate members, between the operating knob and the rubber switch member, and therefore the whole of the switch unit can be formed into a compact design.

A click feeling can be easily produced in a multi-stage manner in accordance with the number of the rubber contact portions.

Therefore, there can be provided the multi-stage click

5